SCIENCE IN THE AGE OF AI

Harrison B. Prosper Florida State University

Colloquium, York University, 16 March 2021



- A Brief History of AI
- Machine Learning
- ML In Science
- o Game Changer
- \circ The Future

What Is Artificial Intelligence?

"...artificial intelligence (AI) refers to any human-like intelligence exhibited by a computer, robot, or other machine." IBM

https://www.ibm.com/cloud/learn/what-is-artificial-intelligence

A BRIEF HISTORY OF AI

Stories about artificially intelligent beings abound in ancient civilizations.

India: spirit movement machines.

Aka: Robots!

Talus, Ancient Greece



Wikimedia Commons

Moveable Type (Gutenberg Bible, 1456)



By NYC Wanderer (Kevin Eng) - originally posted to Flickr as Gutenberg Bible

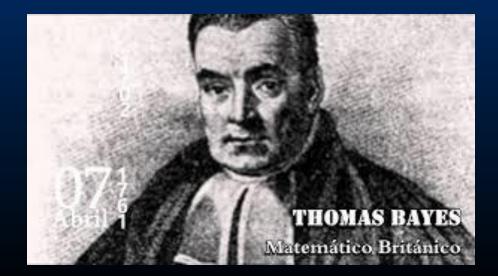
17th century

Many philosophical ideas about knowledge and reason.

18th century

1763 – Thomas Bayes publishes important theorem.

$$P(\boldsymbol{H}|D) = \frac{P(D|\boldsymbol{H})P(\boldsymbol{H})}{P(D)}$$

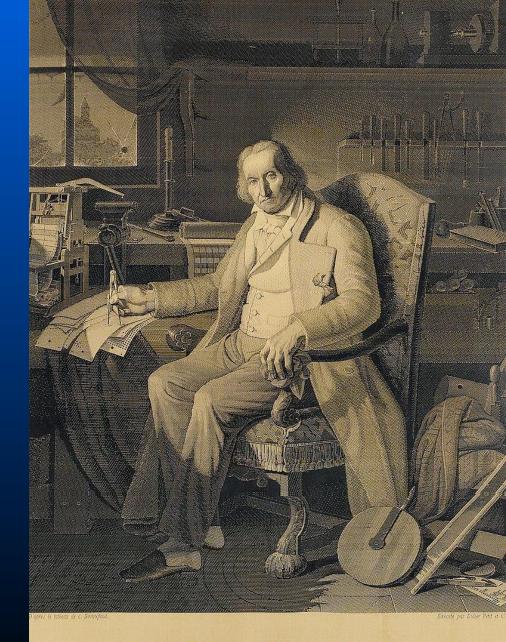


19th century

 1801 – Joseph-Marie Jacquard invents first programmable machine.



Wikimedia commons

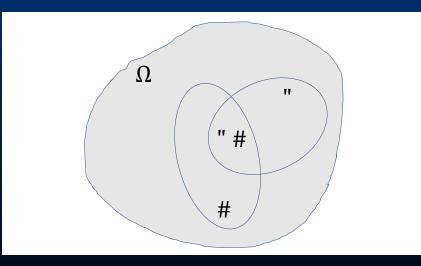


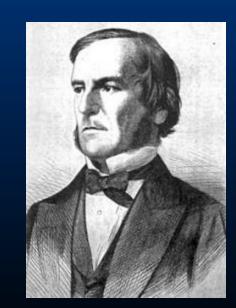
A LA MÉMOIRE DE J. M. JACQUARD.

Né à Lyon le 7 Juillet 1752 Mort le 7 Aout 1854

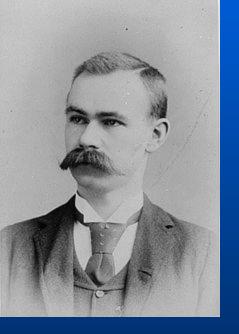
19th century

- 1832 Charles Babbage designs first programmable calculator.
- 1854 George Boole invents algebra of logic.





^{1815 - 1864}



Herman Hollerith (1860 – 1929)

1911: CTR Corp. 1924: IBM

Photo: IBM

1890 US Census



Wikimedia commons

20th century (1900 – 1950)

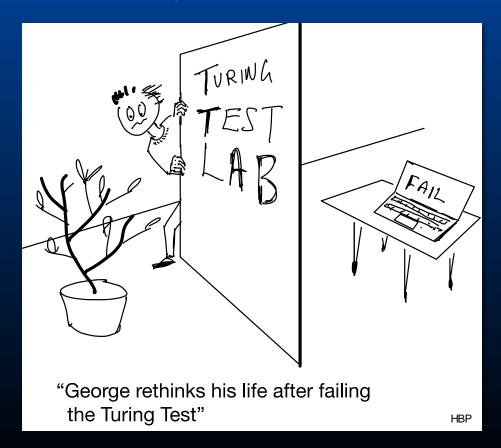
1936 – Alan Turing proposes a universal computing machine.

1943 – Warren McCulloch and Walter Pitts invent neural networks (NN).

It is shown that many particular choices among possible neurophysiological assumptions are equivalent, in the sense that for every net behaving under one assumption, there exists another net which behaves under the other and gives the same results, although perhaps not in the same time. Various applications of the calculus are discussed.

I. Introduction

Theoretical neurophysiology rests on certain cardinal assump tions. The nervous system is a net of neurons, each having a some and an axon. Their adjunctions, or synapses, are always between the axon of one neuron and the soma of another. At any instant a neuron has some threshold, which excitation must exceed to initiate an im pulse. This, except for the fact and the time of its occurrence, is de termined by the neuron, not by the excitation. From the point of ex citation the impulse is propagated to all parts of the neuron. The 20th century (1900 – 1950) • 1950 – The Turing Test



IN THIS BUILDING DURING THE SUMMER OF 1956

JOHN MCCARTHY (DARTMOUTH COLLEGE), MARVIN L. MINSKY (MIT) NATHANIEL ROCHESTER (IBM), AND CLAUDE SHANNON (BELL LABORATORIES) CONDUCTED

THE DARTMOUTH SUMMER RESEARCH PROJECT ON ARTIFICIAL INTELLIGENCE

FIRST USE OF THE TERM "ARTIFICIAL INTELLIGENCE"

FOUNDING OF ARTIFICIAL INTELLIGENCE AS A RESEARCH DISCIPLINE

"To proceed on the basis of the conjecture that every aspect of learning or any other feature of intelligence can in principle be so precisely described that a machine can be made to simulate it."

> IN COMMEMORATION OF THE PROJECT'S 50th ANNIVERSARY JULY 13, 2006

Courtesy John Moor, DOI: <u>10.1609/aimag.v27i4.1911</u>

1997 World chess champion Gary Kasparov defeated by IBM Deep Blue

Feng-hsiung Hsu Murray Campbell IBM Research





Stan Honda/AFP/Getty Images

Source: IBM

Computer Wins on 'Jeopardy!': Trivial, It's Not New York Times, Feb. 17, 2011



Carol Kaelson/Jeopardy Productions Inc., via Associated Press

Ken Jennings: "I felt obsolete" TED Talk

Machine 4, Human 1

2016 – Google's DeepMind AlphaGo program beats Go champion Lee Sodol.



Photograph: Yonhap/Reuters

A Brief History of Al

"York University professors protest their replacement by iPhone 9000s"

Toronto Star, Toronto, Canada, 16 March 2071

MACHINE LEARNING

"That is positively the dopiest idea I have heard." Richard Feynman Thinking Machines Corporation, summer 1983.

Machine Learning



Machine Learning

Deep Learning

Machine Learning

The use of computers to fit highly non-linear, recursively constructed, parameterized functions $f(x, \theta)$ to data.

1. Given an objective function (average of loss function, *L*) $F(\theta) = \frac{1}{T} \sum_{i=1}^{T} L(t_i, f_i)$

2. Solve

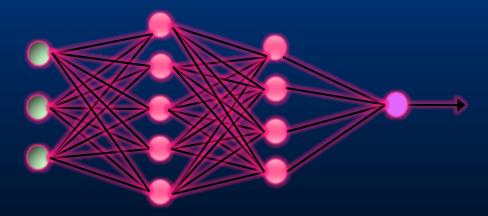
$$\frac{dF}{d\theta} = 0$$

for θ .

3. Commonly used loss function: $L(t, f) = (t - f)^2$

Deep Learning

In 2006, University of Toronto researchers Hinton, Osindero, and Teh* developed a sophisticated, workable, method to train deep neural networks.

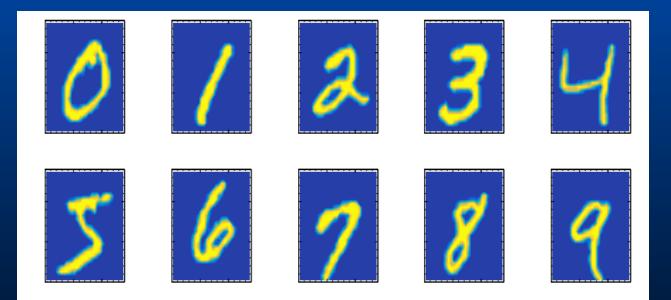






* Hinton, G. E., Osindero, S. and Teh, Y., A fast learning algorithm for deep belief nets, Neural Computation 18, 1527-1554 (2006).

But sophistication is not mandatory! (MNIST)*



*Cireşan DC, Meier U, Gambardella LM, Schmidhuber J., Deep, big, simple neural nets for handwritten digit recognition. Neural Comput. 2010 Dec. 22 (12): 3207-20.

(784, 2500, 2000, 1500, 1000, 500, 10)

1 ²	$l_{_{71}}^{_{1}}$	9 8	ී 9	9	∽ ⁵	в
17		98	5 9	79	35	23
6 9	3 5	9 7	4 9	4 ⁴	Q ²	≤5
4 9	35		49	9 4	0 2	35
ل	9 4	b ⁰	6 6	४ ⁶	1 ¹	≯ 1
16	9 4	60	06	86	79	71
9 49	ಿ 50	5 5 35	? 98	9 79	77 7 17	L 1 6 1
2 7 27	8-8 58	7 ² 78	」 16	6 5	4 4 9 4	6 0

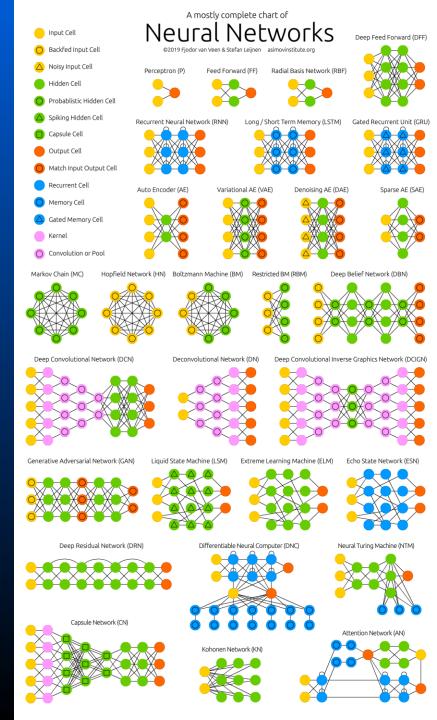
Upper right: correct answer; lower left answer of highest DNN output; lower right answer of next highest DNN output.

The Deep Learning Revolution

Key advances:

- 1. Huge highly effective models
- 2. Huge data sets
- 3. Parallel computation
- 4. Effective optimizers
- 5. Automatic differentiation

Van Veen, F. & Leijnen, S. (2019). The Neural Network Zoo. https://www.asimovinstitute.org/neural-network-zoo



Trail navigation as a classification problem: given video image, Go Straight, Go Left, Go Right

A Machine Learning Approach to Visual Perception of Forest Trails for Mobile Robots

Alessandro Giusti¹, Jérôme Guzzi¹, Dan C. Cireşan¹, Fang-Lin He¹, Juan P. Rodríguez¹ Flavio Fontana², Matthias Faessler², Christian Forster² Jürgen Schmidhuber¹, Gianni Di Caro¹, Davide Scaramuzza², Luca M. Gambardella¹ ML IN SCIENCE

Al in Science: Examples

- Particle Physics
- Astrophysics
- Mathematics

PARTICLE PHYSICS

Collision energy 13 TeV

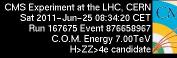
Total stored energy 720 MJ

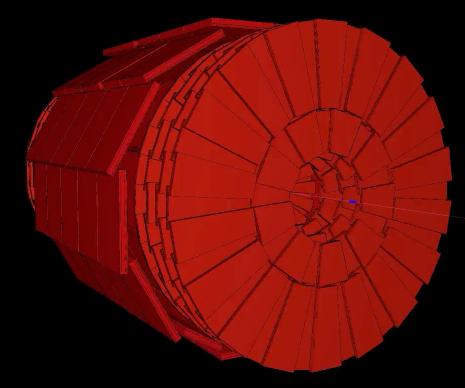
Collision rate 1GHz

Length 26.7 km One Ring to rule them all, One Ring to find them, One Ring to bring them all And in the darkness bind them.

The Large Hadron Collider

Jörg Wenninger



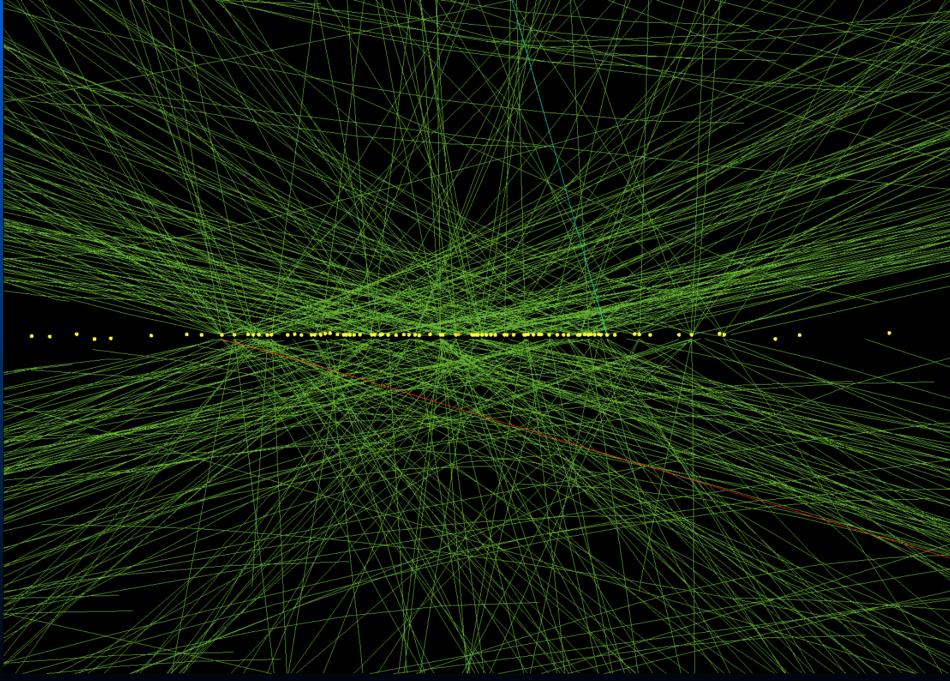




Compact Muon Solenoid

Source: CERN/CMS

32

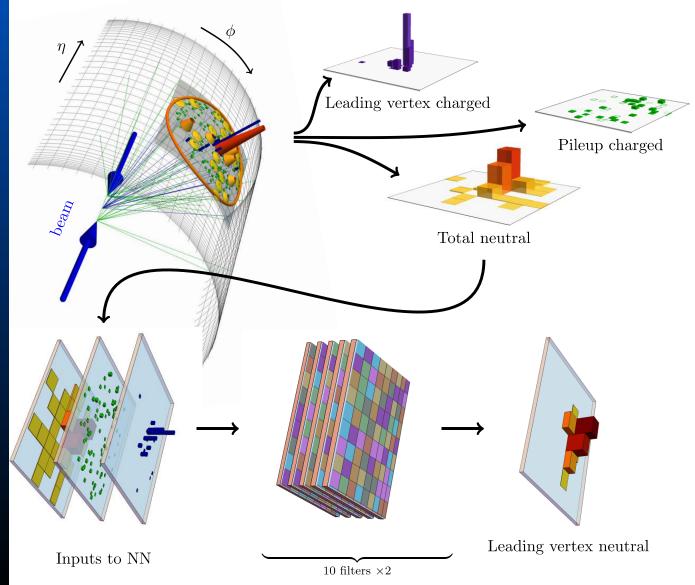


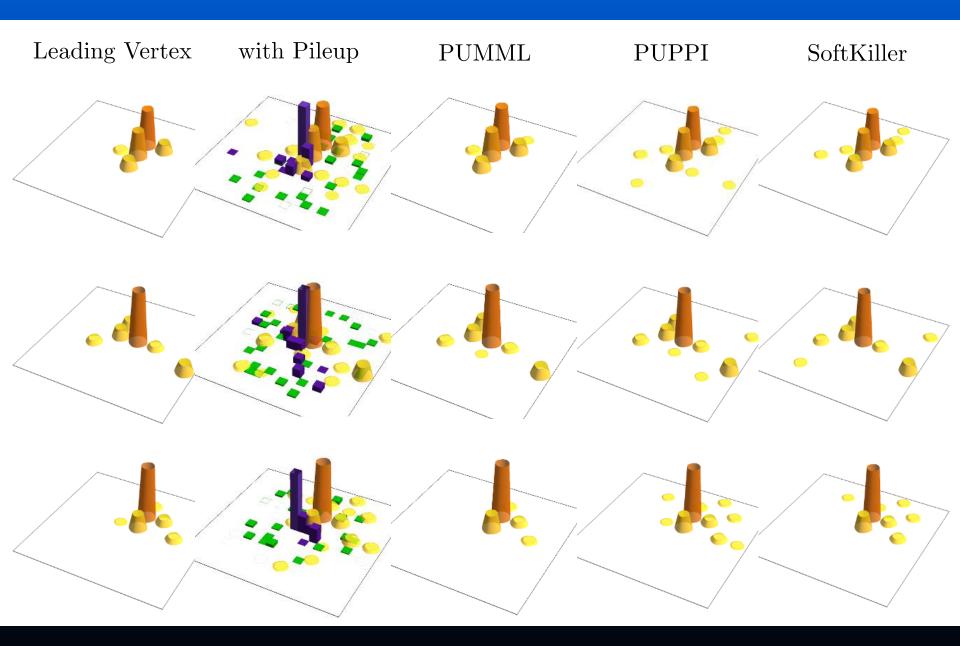
CMS-PHO-EVENTS-2012-006

Pileup Mitigation: PUMML

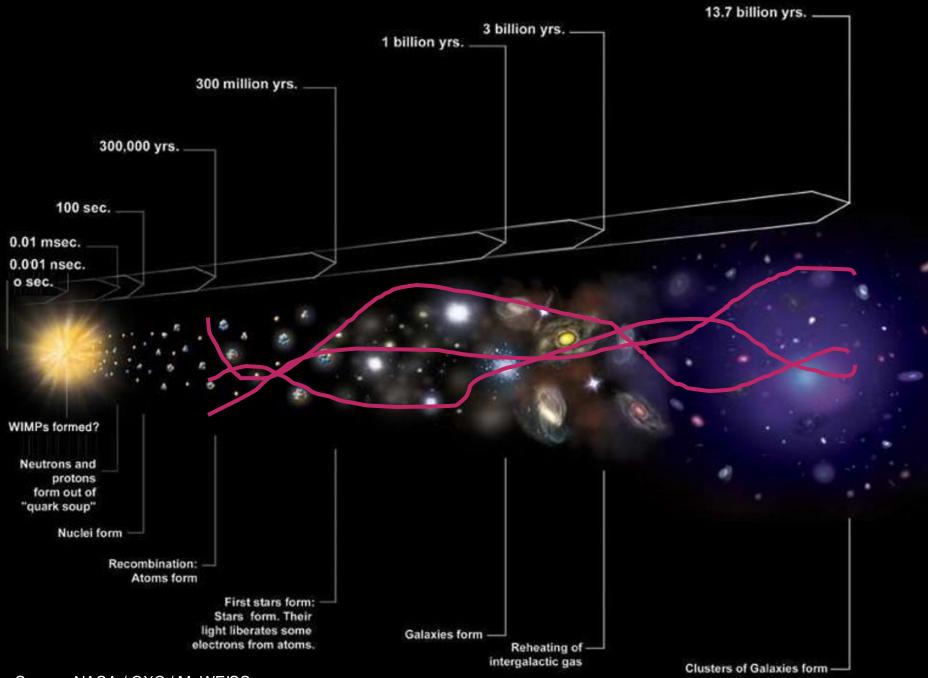
Pileup Mitigation with Machine Learning (PUMML)

Metodiev, Komiske, Nachman, Schwarz, JHEP 12 (2017) 051





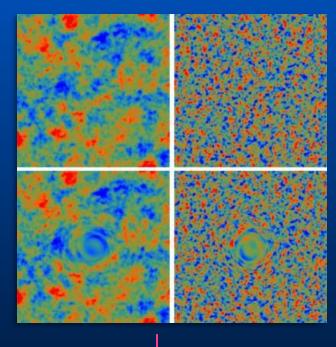




Source: NASA / CXC / M. WEISS

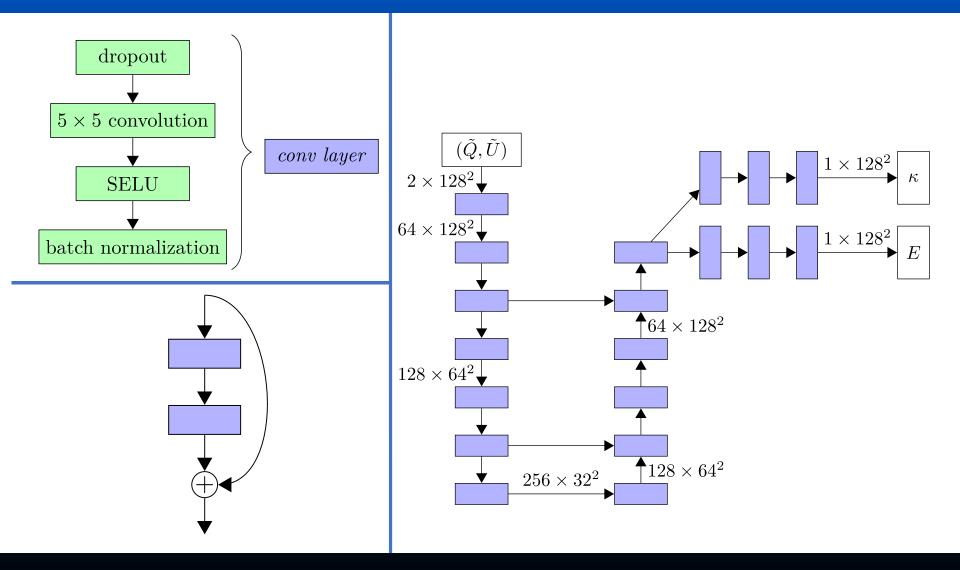
DeepCMB

DeepCMB* is a deep neural network that maps 2 gravitationally lensed, 128 x 128 pixel, images of the CMB to 2 un-lensed, 128 x 128 pixel, images.



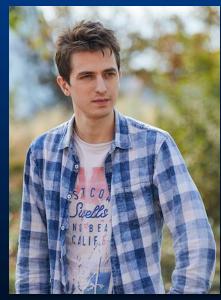
*J. Caldeira, W. L. K. Wu, B. Nord, C. Avestruz, S. Trivedi, K. T. Story, DeepCMB: Lensing Reconstruction of the Cosmic Microwave Background with Deep Neural Networks, **Astronomy and Computing**, 28, July 2019, 100307

Deep CMB: ~ 5 Million Parameters!



MATHEMATICS

In December 2019, Guillaume Lample and François Charton* at Facebook AI Research, Paris, made the startling claim: "We achieve results that outperform commercial Computer Algebra Systems such as Matlab or Mathematica."



Lample

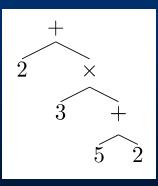


Charton

G. Lample and F. Charton, Deep Learning for Symbolic Mathematics, arXiv: 1912.01412v1.

The key idea is to take the idea of mathematics as a *language* seriously. Then, solving a mathematical problem symbolically is analogous to translating from one language to another or rephrasing a sentence.

Consider the expression $2 + 3 \times (5 + 2)$. It is first written as a tree:



Next, the tree is converted to a sequence: $[+2 \times 3 + 52]$.

Operators, functions, or variables are modeled with specific tokens.

The authors' system simplifies, integrates functions, and solves 1st and 2nd order differential equations.

The training data are pairs (x, t) of correctly formed, *randomly generated*, expressions x with associated solutions t.

For example, for integration, at least two approaches are used:

- 1. Forward: (x, t) where $t = \int x$
- 2. Backward: (x, t) where x = Dt

The Facebook toolkit seq2seq is used to translate one mathematical sequence into another. https://github.com/facebookresearch/fairseq

...and here is a true marvel...

The authors trained their model using the subset of randomly generated functions that sympy can integrate, e.g.,

import sympy as sm
z = sm.Symbol('z')
x = sm.exp(-z)*sm.cos(z)
t = sm.integrate(x, z)
x, t
$$\left(e^{-z}\cos(z), \frac{e^{-z}\sin(z)}{2} - \frac{e^{-z}\cos(z)}{2}\right)$$

Amazingly, the model was able to integrate functions that sympy could not!

GAME CHANGER

ARTICLE

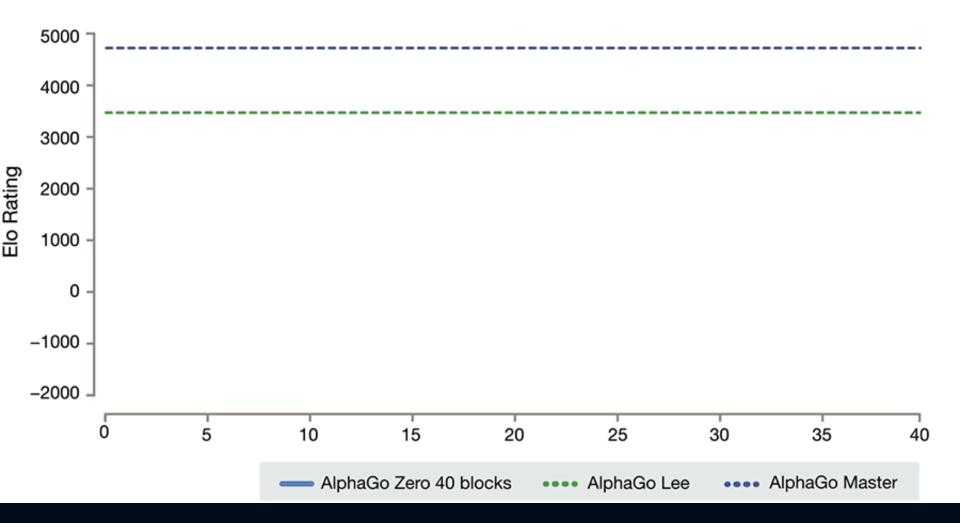
Mastering the game of Go without human knowledge

David Silver¹*, Julian Schrittwieser¹*, Karen Simonyan¹*, Ioannis Antonoglou¹, Aja Huang¹, Arthur Guez¹, Thomas Hubert¹, Lucas Baker¹, Matthew Lai¹, Adrian Bolton¹, Yutian Chen¹, Timothy Lillicrap¹, Fan Hui¹, Laurent Sifre¹, George van den Driessche¹, Thore Graepel¹ & Demis Hassabis¹

A long-standing goal of artificial intelligence is an algorithm that learns, *tabula rasa*, superhuman proficiency in challenging domains. Recently, AlphaGo became the first program to defeat a world champion in the game of Go. The tree search in AlphaGo evaluated positions and selected moves using deep neural networks. These neural networks were trained by supervised learning from human expert moves, and by reinforcement learning from self-play. Here we introduce an algorithm based solely on reinforcement learning, without human data, guidance or domain knowledge beyond game rules. AlphaGo becomes its own teacher: a neural network is trained to predict AlphaGo's own move selections and also the winner of AlphaGo's games. This neural network improves the strength of the tree search, resulting in higher quality move selection and stronger self-play in the next iteration. Starting *tabula rasa*, our new program AlphaGo.

356 | NATURE | VOL 550 | 19 OCTOBER 2017

https://deepmind.com/blog/alphago-zero-learning-scratch/





Science 2071

What might another 50 years of development do to the practice of science?

Potential resources:

- AI-enhanced symbolic mathematics
- High-fidelity, super-fast, simulators
- High-fidelity natural language processors
- Autonomous open data acquisition systems (accelerators, planetwide biosphere-monitors, planet-wide telescope swarms, planetwide personal health monitors, ...)

If some of this remains, in part, public domain and If the Open Science movement takes hold, perhaps science will finally become democratized.



- Autonomous mathematical assistant
- Autonomous transportation
- Direct brain / machine interfaces
- Personal tutors
- Conflict resolution systems



- Al-enhanced micro-drones
- Al-enhanced predictive behavioral agents ("profiling")
- Al-enhanced computer viruses

The Ugly

- The Super-Rich may become the Hyper-Rich.
- The disparity between the haves and have-nots acquires another dimension: Artificial Cognitive Enhancement.
- Social instability arising from acute economic dislocation as AI-enhanced automation displaces more and more traditional jobs.

...and what might happen if we delegate more and more decision making to our tireless assistants: decisions about credit worthiness, loan eligibility, job suitability, likelihood of illness, treatments, life partners, trustworthiness, etc. ...?

MOVIECLIPS.com



The best way to predict the future is to create it. Peter Drucker

THANK YOU!

SOME TECHNICAL MATERIAL

Machine Learning

Machine learning algorithms fall into five broad categories:

- 1. Supervised Learning
- 2. Semi-supervised Learning
- 3. Unsupervised Learning
- 4. Reinforcement Learning
- 5. Generative Learning

Machine Learning

Method

Choose $f(x, \theta^*)$ from M by minimizing the average loss (or empirical risk) $F(\theta) = \frac{1}{T} \sum_{i=1}^{T} L(y_i, f_i) + C(\theta),$

M = Function class

where

 $D = \{(y_i, x_i)\}$ f_i $L(y_i, f_i),$ are training data, $f(x, \theta)$ evaluated at x_i , and the *loss function*, is a measure of the quality of the choice of function.

 $C(\theta)$ is a constraint that guides the choice of $f(x, \theta)$.

The average loss function defines a "landscape" in the *space of functions*, or, equivalently, the space of parameters.

The goal is to find the lowest point in that landscape, by moving in the direction of the *negative* gradient:

$$\theta_i \leftarrow \theta_i - \rho \frac{\partial F(\theta)}{\partial \theta_i}$$

Most minimization algorithms are variations on this theme. **S**tochastic **G**radient **D**escent (SGD) uses random subsets (*batches*) of the training data to provide *noisy* estimates of the gradient in order to increase the chance of escaping from local minima.

Consider $F(\theta)$ in the limit $T \to \infty$

$$F(\theta) = \frac{1}{T} \sum_{i=1}^{T} L(\mathbf{y}_i, \mathbf{f}_i) + C$$
$$\rightarrow \int dx \int dy \, L(\mathbf{y}, \mathbf{f}) \, p(\mathbf{y}, \mathbf{x})$$

Since p(y|x) = p(y,x)/p(x) we can write = $\int dx p(x) \left[\int dy \mathbf{L}(\mathbf{y}, \mathbf{f}) p(y|x) \right]$

We have assumed the influence of the constraint to be negligible in this limit.

Now, consider the *quadratic* loss $L(y, f) = (y - f)^2$

$$F = \int dx \, p(x) \left[\int dy \, \boldsymbol{L}(\boldsymbol{y}, \boldsymbol{f}) \, p(\boldsymbol{y} | \boldsymbol{x}) \right]$$
$$= \int dx \, p(x) \left[\int dy \, (\boldsymbol{y} - \boldsymbol{f})^2 \, p(\boldsymbol{y} | \boldsymbol{x}) \right]$$

and its minimization with respect to the choice of function *f*.

If we change the function f by a small *arbitrary* function δf a small change

$$\delta F = 2 \int dx \, p(x) \delta f \left[\int dy (y - f) p(y|x) \right]$$

will be induced in *F*. In general, $\delta F \neq 0$. However, if the function *f* is flexible enough then we shall be able to reach the minimum of *F*, where $\delta F = 0$. But, in order to guarantee that $\delta F = 0$ for all δf and for all *x* the quantity in brackets must be zero. This yields the important result:

$$f(x,\theta^*) = \int y \, p(y \mid x) \, dy$$

Classification

According to Bayes' theorem

$$p(\mathbf{y}|\mathbf{x}) = \frac{p(\mathbf{x} | \mathbf{y}) p(\mathbf{y})}{\int p(\mathbf{x} | \mathbf{y}) p(\mathbf{y}) d\mathbf{y}}$$

Let's assign the *target* value y = 1 to objects of class S and the target value y = 0 to objects of class **B**.

Then

$$f(x, \theta^*) = \int y \, p(y \mid x) \, dx = p(1|x)$$
$$\equiv p(S|x)$$

That is, the function $f(x, \theta^*)$ equals the class probability.

Classification

1. In summary, the result

$$f(x,\theta^*) = p(S|x) = \frac{p(x|S)p(S)}{p(x|S)p(S) + p(x|B)p(B)}$$

depends only on the form of the loss function, provided that:

- 1. the training data are sufficiently numerous,
- **2.** the function $f(x, \theta)$ is sufficiently flexible, and
- **3.** the minimum of the average loss, *F*, can be found.
- 2. Note, if p(S) = p(B), we arrive at the *discriminant*

$$D(x) = \frac{p(x|S)}{p(x|S) + p(x|B)} \equiv \frac{s(x)}{s(x) + b(x)}$$